MECH6324 - Robot Control

**MECH 6324 (BMEN 6324 and EECS 6324)** Robot Control (3 semester credit hours) Dynamics of robots; methods of control; force control; robust and adaptive control; feedback linearization; Lyapunov design methods; passivity and network control; control of multiple and redundant robots; teleoperation. Prerequisite: **EECS 6331** or **MECH 6300** or **SYSM 6307**. (3-0) T

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