MECH 6324 (BMEN 6324 and EECS 6324) Robot Control (3 semester credit hours) Dynamics of robots; methods of control; force control; robust and adaptive control; feedback linearization; Lyapunov design methods; passivity and network control; control of multiple and redundant robots; teleoperation. Prerequisite: EECS 6331 or MECH 6300 or SYSM 6307. (3-0) T