MECH6324 - Robot Control

MECH 6324 Robot Control (3 semester hours) Dynamics of robots; methods of control; force control; robust and adaptive control; feedback linearization; Lyapunov design methods; passivity and network control; control of multiple and redundant robots; teleoperation. Prerequisite: MECH 6300. (3-0) T (2016-02-05 21:10:50)